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FOUNDATION FOR INTELLIGENT PHYSICAL AGENTS

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FIPA Contract Net Interaction Protocol Specification

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24 based applications. This occurs through open collaboration among its member organizations, which are companies and
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37 represented many countries worldwide. Further information about FIPA as an organization, membership information,
38 FIPA specifications and upcoming meetings may be found on the FIPA Web site at <http://www.fipa.org/>.

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46 **1 FIPA Contract Net Interaction Protocol**

47 The FIPA Contract Net Interaction Protocol (IP) is a minor modification of the original contract net IP pattern¹ in that it
48 adds rejection and confirmation communicative acts. In the contract net IP, one agent (the Initiator) takes the role of
49 manager which wishes to have some task performed by one or more other agents (the Participants) and further wishes
50 to optimise a function that characterizes the task. This characteristic is commonly expressed as the price, in some
51 domain specific way, but could also be soonest time to completion, fair distribution of tasks, etc. For a given task, any
52 number of the Participants may respond with a proposal; the rest must refuse. Negotiations then continue with the
53 Participants that proposed.

54
55 The representation of this IP is given in *Figure 1* which is based on extensions to UML1.x. [Odell2001]. This protocol is
56 identified by the token `fipa-contract-net` as the value of the `protocol` parameter of the ACL message.
57

¹ Originally developed by Smith and Davis.

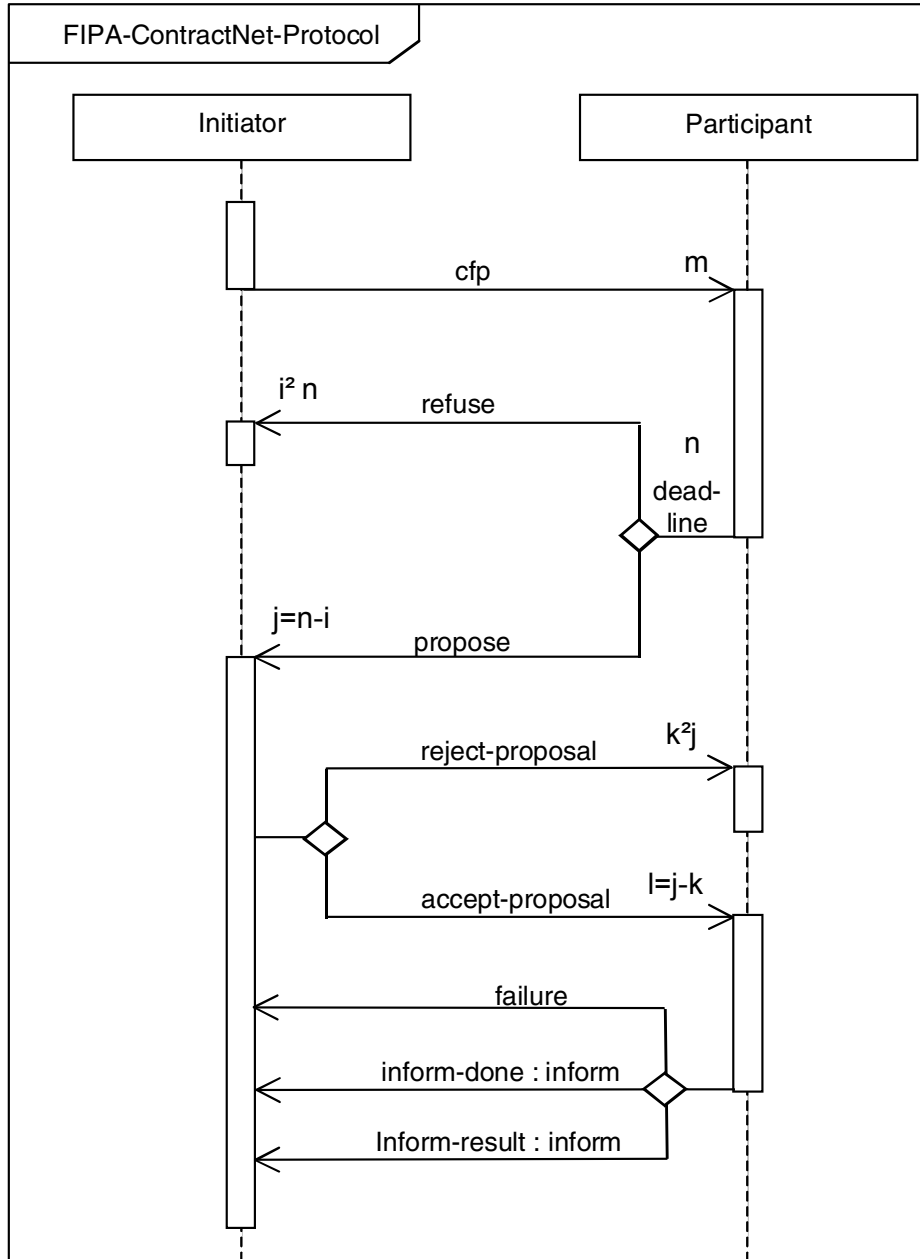


Figure 1: FIPA Contract Net Interaction Protocol

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63 **1.1 Explanation of the Protocol Flow**

64 The Initiator solicits m proposals from other agents by issuing a call for proposals (*cfp*) act (see [FIPA00037]), which
65 specifies the task, as well any conditions the Initiator is placing upon the execution of the task. Participants receiving the
66 call for proposals are viewed as potential contractors and are able to generate n responses. Of these, j are proposals to
67 perform the task, specified as *propose* acts (see [FIPA00037]).

68
69 The Participant's proposal includes the preconditions that the Participant is setting out for the task, which may be the
70 price, time when the task will be done, etc. Alternatively, the $i = n - j$ Participants may *refuse* (see [FIPA00037]) to
71 propose. Once the deadline passes, the Initiator evaluates the received j proposals and selects agents to perform the
72 task; one, several or no agents may be chosen. The l agents of the selected proposal(s) will be sent an *accept-*

73 `proposal` act (see [FIPA00037]) and the remaining k agents will receive a `reject-proposal` act (see [FIPA00037]).
 74 The proposals are binding on the Participant, so that once the Initiator accepts the proposal, the Participant acquires a
 75 commitment to perform the task. Once the Participant has completed the task, it sends a completion message to the
 76 Initiator in the form of an `inform-done` or a more explanatory version in the form of an `inform-result`. However, if
 77 the Participant fails to complete the task, a `failure` message is sent.

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79 Note that this IP requires the Initiator to know when it has received all replies. In the case that a Participant fails to reply
 80 with either a `propose` or a `refuse` act, the Initiator may potentially be left waiting indefinitely. To guard against this,
 81 the `cfp` act includes a deadline by which replies should be received by the Initiator. Proposals received after the
 82 deadline are automatically rejected with the given reason that the proposal was late. The deadline is specified by the
 83 `reply-by` parameter in the ACL message.

84

85 Any interaction using this interaction protocol is identified by a globally unique, non-null `conversation-id` parameter,
 86 assigned by the Initiator. The agents involved in the interaction must tag all of its ACL messages with this conversation
 87 identifier. This enables each agent to manage its communication strategies and activities, for example, it allows an
 88 agent to identify individual conversations and to reason across historical records of conversations.

89

90 In the case of 1:N interaction protocols or sub-protocols the Initiator is free to decide if the same `conversation-id`
 91 parameter should be used or a new one should be issued. Additionally, the messages may specify other interaction-
 92 related information such as a timeout in the `reply-by` parameter that denotes the latest time by which the sending
 93 agent would like to have received the next message in the protocol flow.

94

95 **1.2 Exceptions to Interaction Protocol Flow**

96 At *any* point in the IP, the receiver of a communication can inform the sender that it did not understand what was
 97 communicated. This is accomplished by returning a `not-understood` message. As such, *Figure 1* does not depict a
 98 `not-understood` communication as it can occur at any point in the IP. The communication of a `not-understood`
 99 within an interaction protocol may terminate the entire IP and termination of the interaction may imply that any
 100 commitments made during the interaction are null and void. However, since this IP broadcasts to more than one
 101 Participant, multiple responses are also possible. Each response, then, must be evaluated separately – and some of
 102 these responses might be `not-understood`. However, terminating the entire IP in this case might not be appropriate,
 103 as other Participants may be continuing with their sub-protocols.

104

105 At any point in the IP, the initiator of the IP may cancel the interaction protocol by initiating the meta-protocol shown in
 106 *Figure 2*. The `conversation-id` parameter of the cancel interaction is identical to the `conversation-id` parameter
 107 of the interaction that the Initiator intends to cancel. The semantics of `cancel` should roughly be interpreted as meaning
 108 that the initiator is no longer interested in continuing the interaction and that it should be terminated in a manner
 109 acceptable to both the Initiator and the Participant. The Participant either informs the Initiator that the interaction is done
 110 using an `inform-done` or indicates the failure of the cancellation using a `failure`.

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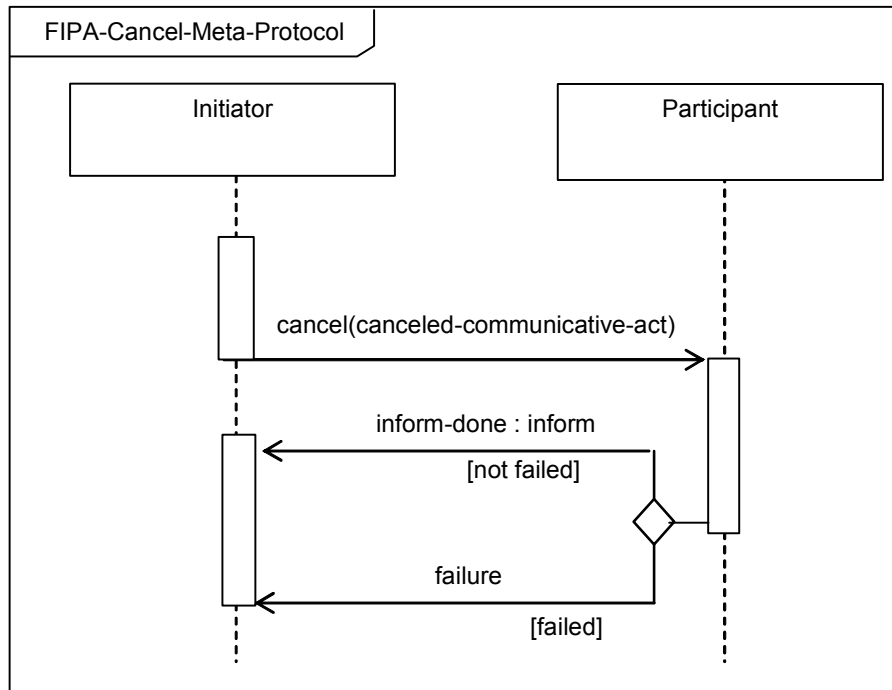


Figure 2: FIPA Cancel Meta-Protocol

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This IP is a pattern for a simple interaction type. Elaboration on this pattern will almost certainly be necessary in order to specify all cases that might occur in an actual agent interaction. Real world issues such as the effects of cancelling actions, asynchrony, abnormal or unexpected IP termination, nested IPs, and the like, are explicitly not addressed here.

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2 References

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[FIPA00037] FIPA Communicative Act Library Specification. Foundation for Intelligent Physical Agents, 2000.

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<http://www.fipa.org/specs/fipa00037/>

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[Odell2001] Odell, James, Van Dyke Parunak, H. and Bauer, B., *Representing Agent Interaction Protocols in UML*.

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140, Berlin, 2001.

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<http://www.fipa.org/docs/input/f-in-00077/>

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127 3 Informative Annex A — ChangeLog

128 3.1 2002/11/01 - version G by TC X2S

- 129 Page 1, line 42: Reworked and expanded the section description of the IP
- 130 Page 2, Figure 1: The communication labeled `inform-ref` was changed to `inform-result` for clarity; the
- 131 purpose of this communication is to inform the initiator of a result and `inform-result`
- 132 implies `inform-done`
- 133 Page 2, Figure 1: The `not-understood` communication was removed
- 134 Page 2, Figure 1: To conform to UML 2, the protocol name was placed in a boundary, `x` is removed from the
- 135 diamonds (`xor` is now the default) and the template box was removed
- 136 Page 2, line 72: Added a new section on Explanation of Protocol Flow
- 137 Page 2, line 72: Reworked and expanded the section on Exceptions of Protocol Flow to incorporate a meta-
- 138 protocol for cancel
- 139 Page 2, line 72: Added a paragraph explaining the `not-understood` communication and its relationship with
- 140 the IP
- 141